NNPDF determination of polarized PDFs at NLO XX International Workshop on Deep-Inelastic Scattering and Related Subjects

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Outline

Introduction

- Why do we need polarized PDFs?
- Issues in Standard PDF determination
- NNDPF fitting approach
 - A general overview
 - Monte Carlo sampling and Neural Networks
- Towards NNPDFpol1.0
 - Experimental dataset and PDF parametrization
 - Results: polarized PDFs and the spin content of the proton
- Conclusions
 - Summary and outlook

1. Introduction

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Why do we need polarized PDFs?

How do quarks and gluons carry proton's spin?

$$a_0 = \Delta \Sigma \equiv \int_0^1 \Delta \Sigma(x) dx = 2 \langle S_z^{ ext{quarks}}
angle \sim 1 \qquad \Delta \Sigma(x) = \sum_{i=u,d,s} (\Delta q_i + \Delta ar q_i)$$

EMC experiment (1988): $a_0 = 0.114 \pm 0.012 \pm 0.026$ "SPIN CRISIS"

$$\langle S_z \rangle = \frac{1}{2} \langle \Delta \Sigma \rangle \longrightarrow \langle S_z \rangle = \frac{1}{2} \langle \Delta \Sigma \rangle + \langle \Delta g \rangle + L_g + L_g$$

Pocus on quark and gluon pieces of the "spin puzzle"



Rich phenomenology, explore QCD beyond helicity-averaged case

Issues in standard PDF determination

- Extraction of a set of functions with error bands from a set of data points.
- We need an error band, i.e. a probability density $\mathcal{P}[\Delta q(x)]$ in the space of PDFs:

$$\langle \mathcal{O} \rangle = \int \mathcal{D} \Delta q \, \mathcal{P}[\Delta q] \mathcal{O}[\Delta q]$$

$$\sigma^2_{\mathcal{O}} = \int \mathcal{D} \Delta q \, \mathcal{P}[\Delta q] (\mathcal{O}[\Delta q] - \langle \mathcal{O}
angle)^2$$

Standard approach

Choose a fixed functional form like

$$\Delta q_i(x, Q_0^2) = A_i x^{b_i} (1-x)^{c_i} (1+\ldots)$$

- 2 Determine best-fit parameters
- Errors determined via Gaussian linear error propagation

But...

- Is the parametrization flexible enough?
- What is the error associated to any particular choice?

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Need to rely on linear error propagation

Simple functional forms vs Neural Networks



- Simple functional forms $\Delta q(x) = Ax^b(1-x)^c P(x)$
 - \longrightarrow systematic underestimation of uncertainties \Rightarrow tolerance
- Artificial Neural Networks as universal interpolants
 - \longrightarrow reduce theoretical bias from choice of PDF functional form

PDF fitting: a new approach

NNPDF: a new approach to PDF fitting based on Monte Carlo sampling and Neural Networks

The NNPDF Collaboration, Nucl.Phys. B849 (2011) 296, 1101.1300 NNPDF2.1 NNPDF2.1 CT10 CT10 MSTW08 MSTW08 хΣ (x, Q²) xg (x, Q²) 2 -2 10-3 10⁻² 10⁻¹ 10-5 10.1 10 104 10.4 10-3

Successfully applied in the unpolarized case: most recent global fit NNPDF2.1 Routinely used in LHC data analysis and theory prediction

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NNPDFpol1.0

2. NNPDF fitting approach

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A general overview on the recipe



Ingredients: Monte Carlo sampling and Neural Networks

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Ingredient 1: Monte Carlo sampling of experimental data

MONTE CARLO SAMPLING

 Sample the probability density *P*[Δq] in the space of functions assuming multi-Gaussian data probability distribution

$$g_{1,p}^{(\text{art}),k}(x,Q^2) = (1 + r_{k,N}\sigma_N) \left[g_{1,p}^{(\text{exp})}(x,Q^2) + r_{k,t}\sigma_t(x,Q^2) \right]$$

 r_k : Gaussian random numbers σ_N quadratic sum of normalization errors σ_t : total error (summing in quadrature statistical and systematic errors)

• Generate MC ensemble of N_{rep} replicas with the data probability distribution

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MAIN FEATURES

• Expectation values for observables are Monte Carlo integrals

$$\langle \mathcal{O}[\Delta q]
angle = rac{1}{N_{\mathsf{rep}}} \sum_{k=1}^{N_{\mathsf{rep}}} \mathcal{O}[\Delta q_k]$$

- ... and the same is true for errors, correlations etc.
- No need to rely on linear propagation of errors
- Possibility to test for non-Gaussian behaviour in fitted PDFs



 Require the average over the replicas reproduces central values and errors of the original experimental data to desired accuracy — determine size of the sample

• Accuracy of few % requires \sim 1000 replicas

A convenient functional form providing redundant and flexible parametrization used as a generator of random functions in the PDF space



$$\xi_i^{(l)} = g\left(\sum_{j}^{n_l-1} \omega_{ij}^{(l-1)} \xi_j^{(l-1)} - \theta_i^{(l)}\right)$$
$$g(x) = \frac{1}{1 + e^{-x}}$$

- made of neurons grouped into layers (define the architecture)
- each neuron receives input from neurons in preceding layer (feed-forward NN)
- activation determined by parameters (weights and thresholds)
- activation determined according to a non-linear function

NEURAL NETWORKS

• Parametrize each polarized PDF replica with flexible Neural Network

DSSV, AAC, LSS, BB	NNPDFpol
$\mathcal{O}(10-20)$ parameters	$\mathcal{O}(200)$ parameters

- Train NN to determine the best fit for each replica
- Compute an ensemble of observables and compare to experimental data

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MAIN FEATURES

- Only require smoothness of the fitted function
- Do not require any other prejudice on a priori functional form
- Reduce the bias associated to the choice of some functional form
- Given smoothness, the algorithm provided by NN is efficient and can be easily implemented with other algorithms (e.g. genetic algorithms)

3. Towards NNPDFpol1.0

Experimental dataset



$$g_1(x, Q^2) = A_1(x, Q^2) \frac{F_2(x, Q^2)}{2x(1 + R(x, Q^2))} (1 + \gamma^2) \qquad \gamma^2 = \frac{4M_N^2 x^2}{Q^2}$$

Experimental dataset



- $Q^2 > 1 Gev^2$
- $W^2 = Q^2(1-x)/x \ge 6.25 GeV^2$ (C. Simolo, Ph.D. Thesis. arXiv:0807.1501)

Four polarized PDFs (gluon + linear combinations of light quarks)

• singlet
$$\Delta \Sigma(x) \equiv \sum_{i=1}^{n_f} (\Delta q_i(x) + \Delta \bar{q}_i(x))$$

• gluon
$$\Delta g(x)$$

- triplet $\Delta T_3(x) \equiv (\Delta u(x) + \Delta \overline{u}(x)) (\Delta d(x) + \Delta \overline{d}(x))$
- octet $\Delta T_8(x) \equiv (\Delta u(x) + \Delta \overline{u}(x)) + (\Delta d(x) + \Delta \overline{d}(x) 2(\Delta s(x) + \Delta \overline{s}(x)))$
- 2 At initial scale $Q_0^2 = 1 GeV^2$ and using $\alpha_s(M_Z^2) = 0.119$
- Assume all heavy quarks are generated radiatively
- Must satisfy theoretical constraints:
 - Sum rules

$$\left[\Delta T_{3}(Q_{0}^{2})\right] \equiv \int_{0}^{1} dx \Delta T_{3}(x, Q_{0}^{2}) = a_{3} \qquad \left[\Delta T_{8}(Q_{0}^{2})\right] \equiv \int_{0}^{1} dx \Delta T_{8}(x, Q_{0}^{2}) = a_{8}$$

· Positivity bound for all proton, neutron and deuteron targets

$$|g_1(x,Q^2)| \leq F_1(x,Q^2)$$

Preprocessing: basic idea

- Each polarized PDF parametrized with a multi-layer feed-forward NN. All NN have the same architecture (2-5-3-1).
- Parametrization supplemented with a preprocessing polynomial: exponents m and n randomly choosen in fixed intervals; the NN only fits the deviation from this function.

$$\begin{split} \Delta\Sigma(x,Q_0^2) &= (1-x)^{m_{\Delta\Sigma}} x^{-n_{\Delta\Sigma}} NN_{\Delta\Sigma}(x) \\ \Delta g(x,Q_0^2) &= (1-x)^{m_{\Delta\mathfrak{g}}} x^{-n_{\Delta\mathfrak{g}}} NN_{\Delta\mathfrak{g}}(x) \\ \Delta T_3(x,Q_0^2) &= A_{\Delta T_3} (1-x)^{m_{\Delta} T_3} x^{-n_{\Delta} T_3} NN_{\Delta T_3}(x) \\ \Delta T_8(X,Q_0^2) &= A_{\Delta T_8} (1-x)^{m_{\Delta} T_8} x^{-n_{\Delta} T_8} NN_{\Delta T_8}(x) \end{split}$$

Overall normalization constant factored out for triplet and octet. Determined by imposing the sum rules.

$$A_{\Delta T_{3}} = \frac{a_{3}}{\int_{0}^{1} dx [(1-x)^{m_{\Delta T_{3}}} x^{-n_{\Delta T_{3}}} NN_{\Delta T_{3}}(x)]}$$

$$A_{\Delta T_8} = \frac{a_8}{\int_0^1 dx [(1-x)^{m_{\Delta} T_8} x^{-n_{\Delta} T_8} N N_{\Delta T_8}(x)]}$$

Preprocessing: effective asymptotic exponents



Effective exponents always contained in the preprocessing exponents range The polarized PDF is driven only by experimental data

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NNPDFpol1.0: results



Much larger error bands for Singlet and Gluon

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NNPDFpol1.0: results



Triplet agrees with DSSV08 fit, but does not with BB10 fit Much larger error band for Octet

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NNPDFpol1.0: results





Singlet and Gluon first moments in $\overline{\text{MS}}$ scheme at $Q_0^2 = 1 \text{ GeV}^2$

	NNPDFpol1.0	DSSV08	AAC08
[ΔΣ]	0.32 ± 0.11	0.26 ± 0.03	0.26 ± 0.06
$[\Delta g]$	-0.2 ± 1.1	-0.12 ± 0.12	0.40 ± 0.28

Notice the large uncertainty on the first moments: Singlet between two and four times Gluon almost one order of magnitude

$$egin{aligned} \langle S_z
angle &= rac{1}{2} \langle \Delta \Sigma
angle + \langle \Delta g
angle + \mathcal{L}_q + \mathcal{L}_g \ &rac{1}{2} = (-0.1 \pm 1.1) + \mathcal{L}_q + \mathcal{L}_g \end{aligned}$$

Gluon uncertainty dominates the contribution to proton's spin

4. Conclusions

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Summary

- The NNPDF technology provides a statistically sound procedure for PDF fitting
- **2** NNPDFpol1.0 is the first polarized parton determination using NNPDF approach
- The analysis from inclusive DIS data leads to
 - able to discriminate Triplet (agreement with DSSV08, not with BB10)
 - large uncertainties on Singlet and Octet and very large on Gluon
 - uncertainty on Singlet first moment between two and four times bigger
 - uncertainty on Gluon first moment almost one order of magnitude bigger

Outlook

- Include data sets from other processes (open charm and jet production with fixed target, inclusive jet production, W boson production at RHIC, ...)
- 2 Determine the strong-coupling constant from polarized DIS data
- Investigate the sensitivity of polarized data to a_3 and a_8 axial constants

Final remarks

Summary

- In the NNPDF technology provides a statistically sound procedure for PDF fitting
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Thank you for your attention!

5. Backup

Image: A math a math

First stage: first moments of polarized PDFs and polarized sum rules (last 25 years)

- Second stage: polarized PDF fits from global NLO QCD analysis (last ~15 years) → different choice of datasets, parton parametrization, treatement of higher twists, ... ABFR (arXiv:hep-ph/9803237, 1998), BB (arXiv:1005.3113, 2010) (DIS only); AAC (arXiv:0808.0413, 2008), LSS (arXiv:1010.0574, 2010) (DIS+SIDIS); DSSV (arXiv:0904.3821, 2009) (DIS+SIDIS+pp)
- ③ Third stage: provide uncertainties on polarized PDFs (last ~10 years) → Gaussian error propagation, Lagrange multiplier + Hessian method; fit with orthogonal polynomials (arXiv:1011.4873, 2010)

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Monte Carlo sampling: more detail

• The k-th MC replica is generated assuming a multi-Gaussian distribution

$$g_{1,i}^{(\text{art}),k}(x,Q^2) = (1 + r_{k,N}\sigma_N) \left[g_{1,p}^{(\text{exp})}(x,Q^2) + r_{k,t}\sigma_t(x,Q^2) \right]$$

- r_k : Gaussian random numbers σ_N quadratic sum of normalization errors σ_t : total error (summing in quadrature statistical and systematic errors)
- Require the average over the replicas reproduces central values and errors of the original experimental data to desired accuracy → determine size of the sample

r [g1]	1.00
$\left\langle \sigma^{(\exp)} \right\rangle_{dat}$ (%)	0.13E+03
$\left< \sigma^{(\text{gen})} \right>_{\text{dat}}$	0.11E+03
$r\left[\sigma^{(gen)} ight]$ (%)	0.10E+01
$\left< \rho^{(\exp)} \right>_{dat}$	0.64E-01
$\left< \rho^{(\text{gen})} \right>_{\text{dat}}$	0.64E-01
$r\left[\rho^{(\text{gen})}\right]$	0.98E+00
$\left< cov^{(exp)} \right>_{dat}$	0.25E-01
$\left< cov^{(gen)} \right>_{dat}$	0.25E-01
$r \left[\operatorname{cov}^{(\operatorname{gen})} \right]^{-1}$	0.10E+01

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Monte Carlo vs Hessian PDF uncertainties



HERA-LHC 2009 PDf benchmarks

- H1PDF2000 fit done with Hessian method and with Monte Carlo method
- The standard deviation of the 100 PDF replicas (MC method) is in perfect agreement with Hessian errors with $\Delta\chi^2 = 1$
- The MC method to estimate PDF uncertainties reproduces Hessian result when global χ^2 is quadratic

In Mellin space the DGLAP equations

$$\mu^{2} \frac{\partial}{\partial \mu^{2}} \Delta q_{NS}^{\pm,\nu}(N,\mu^{2}) = \Delta \gamma_{NS}^{\pm,\nu} q_{NS}^{\pm,\nu}(N,\mu^{2})$$

$$\mu^{2} \frac{\partial}{\partial \mu^{2}} \begin{pmatrix} \Delta \Sigma \\ \Delta g \end{pmatrix} (N,\mu^{2}) = \begin{pmatrix} \Delta \gamma_{qq}(N,\alpha_{s}(Q^{2})) & \Delta \gamma_{qg}(N,\alpha_{s}(Q^{2})) \\ \Delta \gamma_{gq}(N,\alpha_{s}(Q^{2})) & \Delta \gamma_{gg}(N,\alpha_{s}(Q^{2})) \end{pmatrix} \begin{pmatrix} \Delta \Sigma \\ \Delta g \end{pmatrix}$$

can be solved analitically

$$\Delta q_{NS}^{\pm,
u}(N,Q^2) = \Gamma_{NS}^{\pm,
u}(N,a_s,a_0)\Delta q_{NS}^{\pm,
u}(N,Q_0^2)$$
, $a_s \equiv lpha_s/2\pi$

where, at NLO,

$$\Gamma_{NS,NLO}^{\pm,\nu}(N,a_s,a_0) = \exp\left\{\frac{U_1^{\pm,\nu}}{b_1}\ln\left(\frac{1+b_1a_s}{1+b_1a_0}\right)\right\} \left(\frac{a_s}{a_0}\right)^{-R_0^{NS}}$$

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NNPDF NLO polarized PDF evolution (**Fast Kernel method**) benchmarked with the Les Houches PDF benchmarks (G. Salam and a. Vogt, hep-ph/0511119)

x	$\epsilon_{\mathrm{rel}}(\Delta u_V)$	$\epsilon_{\mathrm{rel}}\left(\Delta d_{V}\right)$	$\epsilon_{\mathrm{rel}} \left(\Delta \Sigma \right)$	$\epsilon_{\mathrm{rel}}\left(\Delta g\right)$
10^-3	1.110^{-4}	9.210^{-5}	9.910^{-5}	1.110^{-4}
10^2	1.410^{-4}	1.910^{-4}	3.510^{-4}	9.310^{-5}
0.1	1.210^{-4}	1.610^{-4}	5.410^{-6}	1.710^{-4}
0.3	2.310^{-6}	1.110^{-5}	7.510^{-6}	1.710^{-5}
0.5	5.610^{-6}	9.610^{-6}	1.610^{-5}	2.510^{-5}
0.7	1.210^{-4}	9.210^{-7}	1.610^{-4}	7.810^{-5}
0.9	3.510^{-3}	1.110^{-2}	4.110^{-3}	7.810^{-3}

Very accurate evolution!



Kinematical cuts exclude the largest-x and smallest- Q^2 data region, where the TMC effects are most important Moderate impact of TMC corrections (small percent at small Q^2)

NN are flexible tools can learn fluctuations

2 Cross-validation method

- divide data into two subsets (training & validation)
- train the NN on training subset
- compute χ^2 for each subset
- stop when χ² of validation subset no longer decreases (NN are learning fluctuations!)

UNDERLEARNING



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- Set Neural Network parameters randomly
- Make clones of the parameter vector and mutate them
- Define a figure of merit or error function for the k-th replica

$$E^{(k)} = \frac{1}{N_{\text{rep}}} \sum_{i,j=1}^{N_{\text{rep}}} \left(F_i^{(\text{art})(k)} - F_i^{(\text{net})(k)} \right) \left((\text{cov}_{t_0})^{-1} \right)_{ij} \left(F_j^{(\text{art})(k)} - F_j^{(\text{net})(k)} \right)$$

$$(\text{cov}_{t_0})_{ij} = \sigma_{N,i}\sigma_{Nj}g_{1i}^{(0)}g_{1j}^{(0)} + \delta_{ij}\sigma_{i,tot}^2$$

is the covariance matrix including normalization errors using the t_0 method (arXiv:0912.2276)

• Select the best ones and perform other manipulations (crossing, mutating, ...) until stability is reached

NNPDFpol1.0: global χ^2





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NNPDFpol1.0

NNPDFpol1.0: individual experiments χ^2



- No evidence of any specific dataset being inconsistet with each other
- $\bullet\,$ Distribution of individual χ^2 values broadly consistent with statistical expectations

Preprocessing: effective asymptotic exponents



Effective exponents always contained in in the preprocessing exponents range The polarized PDF is driven only by experimental data

Preprocessing: effective asymptotic exponents



Effective exponents always contained in in the preprocessing exponents range The polarized PDF is driven only by experimental data

NNPDFpol1.0: more results



Substantial agreement for Singlet Gluon essentially unconstrained

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NNPDFpol1.0: more results



Substantial agreement for Octet, but with larger error band Triplet slightly bigger

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NNPDFpol1.0: 68% confidence levels



comparison between 1σ error bands and 68% confidence level test for non-Gaussian behaviour

sizeable deviations from Gaussian behaviour in the extrapolation region

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NNPDFpol1.0

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