Progress in neural parton distributions

Juan Rojo Chacón LPTHE - Université Paris VI et Paris VII

Deep Inelastic Scattering 2007 Workshop, April 18th 2007.



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The NNPDF Collaboration: Luigi Del Debbio, Stefano Forte, José I. Latorre, Andrea Piccione and Juan Rojo, (2007: +) Richard D. Ball, Alberto Guffanti and Maria Ubiali. Resuls based on:

- 1. JHEP 02 (2002) 062 [arXiv:hep-ph/0204232].
- 2. JHEP 05 (2005) 080 [arXiv:hep-ph/0501067].
- 3. Neural network determination of parton distributions: the nonsinglet case, JHEP 07 (2007) 039 [arXiv:hep-ph/0701127].

Introduction

Methodological issues

Stopping criterion Stability estimators

The nonsinglet case

Status of the singlet case

Conclusions and outlook



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Basic Idea: Monte Carlo sampling coupled to Neural Network interpolation

- Generate a set of Monte Carlo replicas σ^(k)(p_i) of the original data set σ^(data)(p_i), representation of P[σ(p_i)] at discrete set of points p_i
- Train a neural net for each pdf on each replica, obtaining a representation of the pdfs q_i^{(net)(k)}
- The set of neural nets is a representation of the probability density:



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What is a neural net? Just a particular choice of function

$$\xi_i^{(l+1)} = g\left(\sum_{j=1}^{n(l)} \omega_{ij}^{(l)} \xi_j^{l}\right), \quad g(x) = \frac{1}{1+e^x}, \quad l=2,\ldots,L$$

where $\omega_{ii}^{(l)}$ are the *weights* and $\xi_i^{(l+1)}$ the *activation state* of each neuron.

- Functional form $q(x) = f[x, \{A_i\}] = A_1 x^{A_2} (1-x)^{A_3}$
- Neural net $q(x) = f[x, \{\omega_{ij}\}] = g\left(\sum_{j=1}^{n(L-1)} \omega_{ij}^{(L-1)} \xi_j^{(L-1)}\right), \ \xi_1^{(1)} = x$

Simple net: Architecture 2-1 $\rightarrow \xi_1^{(2)} = \left[1 + \exp\left(\omega_{11}^{(1)}\xi_1^{(1)} + \omega_{12}^{(1)}\xi_2^{(1)}\right)\right]^{-1}$



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Many different ingredients in the neural Monte Carlo approach to parton distributions: artificial data generation, neural network training, genetic minimization, preprocessing, result validation ...

Let us concentrate on a couple of the newest ones:

- Stopping criterion
- Stability estimators

N.B. Unless otherwise specified, results shown belong to hep-ph/0701127

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In a standard fit, look for minimum χ^2 for given parametrization. However ...

- If basis too large \rightarrow convergence never reached
- ▶ If basis too small → parametrization bias

How can one obtain an unbiased compromise? For neural nets, smoothness decreases as fit quality improves...

 \rightarrow Stop before fitting statistical noise (overlearning).

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Ex.: fitting a neural net to signal+noise pseudodata.



Underlearning

(Gross features of data already captured)

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Stopping criterion				

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Proper learning

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Overlearning

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So stop the fit before overlearning sets in … How does this work in practice? At each Genetic Algorithm iteration, χ^2 either decreases or unchanged

- 1. Divide the data set into training and validation sets
- 2. Minimize χ^2 of training set, monitor χ^2 of validation set
- 3. Stop minimization when validation χ^2 begins to rise

The transition from the underlearning to the overlearning regime monotonic with neural networks.

N.B. This stopping criterion could also be applied using standard polynomials (but impractical, a very large number of parameters required + non monotonic transition to overlearning regime).

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Let us see in practice how the overlearning stopping criterion works:

On your marks, get ready ...



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Let us see in practice how the overlearning stopping criterion works: Compare training and validation χ^2 .

(*N.B.* With GA, the network fit quality improves monotonically with the number of iterations)



Underlearning, continue the minimization

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Let us see in practice how the overlearning stopping criterion works:



Stop!

Onset of overlearning, stop the minimization.

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Progress in neural parton distributions



Let us see in practice how the overlearning stopping criterion works:



Too late!

Deep in the overlearning region, fitting statistical noise ...

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Stopping criterior	1			

Does it work?



1. Poissonian distribution of training lenghts

- 2. For best fit, average χ^2 of replicas \sim 2, while when averaging over replicas $\chi^2 \sim$ 1.
- 3. Total training time is optimized (never underlearn nor overlearn) \rightarrow efficient neural fitting.

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Check stability and accuracy of our results (both for central values and for errors) when parameters of fit modified

Define RMS distance

$$\langle d[q]
angle = \sqrt{\left\langle \frac{\left(\langle q_i
angle_{(1)} - \langle q_i
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ight)^2}{\sigma^2[q_i^{(1)}] + \sigma^2[q_i^{(2)}]}
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where $\sigma[q_i] = \text{error on } \langle q_i \rangle = \text{error on } q_i / \sqrt{N_{\text{rep}}}$. Compute $\langle d[q] \rangle$ and $\langle d[\sigma] \rangle$ both in data region and in extrapolation region. Statistical expectations:

- For statistically equivalent fits (different set of MC replicas, different net architecture) we expect ⟨d[q]⟩ ~ 1, ⟨d[σ]⟩ ~ 1.
- For statistically nonequivalent fits (different perturbative order, different α_s value) we expect (e.g. for central values)

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Indeed we observe the expected behavior:

Architecture	2-4-3-1 vs. 2-5-3-1	Perturbative order	LO vs. NLO
$\langle d[q] \rangle_{\rm dat}$	0.9	$\langle d[q] \rangle_{\rm dat}$	10.2
$\left< d\left[q\right] \right>_{\mathrm{extra}}$	0.9	$\left< d\left[q ight] \right>_{ m extra}$	1.2
$\langle d\left[\sigma_q\right] angle_{\mathrm{dat}}$	0.9	$\langle d\left[\sigma_{q} ight] angle_{\mathrm{dat}}$	2.2
$\left\langle d\left[\sigma_{q}\right] \right\rangle_{\mathrm{extra}}$	1.4	$\left\langle d\left[\sigma_{q} ight] ight angle_{\mathrm{extra}}$	1.3

Independence of the net architecture

 \rightarrow Explicit confirmation of parametrization invariance : stability of both central values and errors!

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$\langle d\left[\sigma_{q}\right] angle_{\mathrm{dat}}$	0.9	$\langle d \left[\sigma_q \right] \rangle_{\text{dat}}$	2.2
$\left\langle d\left[\sigma_{q}\right] \right\rangle_{\mathrm{extra}}$	1.4	$\left\langle d\left[\sigma_{q} ight] ight angle_{\mathrm{extra}}$	1.3

Independence of the net architecture

 \rightarrow Explicit confirmation of parametrization invariance : stability of both central values and errors!

Indeed we observe the expected behavior:

Architecture	2-4-3-1 vs. 2-5-3-1	Perturbative order	LO vs. NLO
$\langle d[q] \rangle_{\rm dat}$	0.9	$\langle d[q] \rangle_{\rm dat}$	10.2
$\left\langle d\left[q\right] \right\rangle_{\mathrm{extra}}$	0.9	$\left< d\left[q ight] \right>_{ m extra}$	1.2
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The nonsinglet case

Juan Rojo-Chacón

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- 1. Data: $F_2^p(x, Q^2) F_2^d(x, Q^2)$ from NMC and BCDMS (483 points with $Q^2 \ge 3 \text{ GeV}^2$)
- 2. Determination of $q^{NS}(x, Q_0^2) \equiv (u + \bar{u} (d + \bar{d}))(x, Q_0^2)$ at $Q_0^2 = 2$ GeV² at LO, NLO, NNLO, and for different values of $\alpha_s(M_Z^2)$.
- 3. New fast and efficient implementation of NNLO parton evolution (mixed x/N space), benchmarked with the LH tables (Salam/Vogt, 2006).

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Results available from http://sophia.ecm.ub.es/nnpdf

See hep-ph/0701127 for all the technical details ...

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A (1) > A (2) >

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Theoretical uncertainties



1. Same quality of the fit ($\chi^2/\textit{N}_{\rm dat}\sim$ 0.75) at LO, NLO, NNLO

- 2. NNLO terms negligible within errors
- 3. LO/NLO differ within 3 σ : NLO terms absorbed in BC.

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Determination of $\alpha_s(M_Z^2)$ - I

We do not fit $\alpha_s(M_Z^2)$ together with $q_{\rm NS}(x, Q_0^2)$ but take it from world average: $\alpha_s(M_Z^2)_{\rm NLO} = 0.118 \pm 0.002$.

$\alpha_s(M_Z^2)$	0.116	0.118	0.120
χ^2	0.743	0.750	0.744
$\left< d\left[q\right] \right>_{\mathrm{dat}}$	3.8	-	4.1
$\left< d\left[q\right] \right>_{ m extra}$	0.8	-	0.7
$\langle d \left[\sigma_q \right] \rangle_{\text{dat}}$	1.6	-	2.4
$\left\langle d\left[\sigma_{q}\right] \right\rangle_{\mathrm{extra}}$	1.4	-	1.5

Fit results suggest that $\alpha_s(M_Z^2)$ from NS data has larger uncertainties than those of world average.

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Kinematical cuts



Uncertainty in extrapolation region (small x) increases when kinematical cut in Q^2 is raised (as it should be!).

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The nonsinglet case: Applications (preliminary)

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Determination of $\Delta \chi^2$

Many hints that some data sets used in global fits inconsistent \rightarrow Some uncertainties underestimated \rightarrow The $\Delta \chi^2$ which corresponds to $1 - \sigma$ errors on PDFs no longer textbook value $\Delta \chi^2 = 1$.

In our approach $\Delta \chi^2$ can be quantitatively determined \rightarrow The result will tell whether inconsistent data are present. Compute variance σ_{χ^2} of the χ^2 when fit repeated many times. For reference fit (preliminary result):

$$\Delta\chi^2\equiv\sqrt{N_{
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The result implies that most Non Singlet world data form a consistent data set, but some subset inconsistent (subset of NMC data).

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Aethodological issues

Status of the singlet case

Conclusions and outlook

Determination of $\alpha_s(M_Z^2)$ - II



 $\alpha_s(M_Z^2)$ can be determined from NS data \rightarrow uncertainty larger than 0.002. Due to lack of param. bias? Compare with parametrization-independent determination from NS truncated moments \rightarrow $\alpha_s(M_Z^2)_{\rm NLO} = 0.124 + 0.004 - 0.007$ (exp.), S. Forte et al., hep-ph/0205286.

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Status of the singlet case

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The singlet case

▶ Data sets: SLAC, NMC, BCDMS structure function F₂(x, Q²) and HERA reduced cross sections σ̃^{NC}(x, Q²) and σ̃^{CC}(x, Q²).

Fitted parton distributions (neural nets):

$$\Sigma(x, Q_0^2)$$
, $q_{\rm NS}(x, Q_0^2)$, $g(x, Q_0^2)$

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Increased manpower of the NNPDF collaboration (RDB, AG, MU)

- October 2006 February 2007: Nonsinglet code extended to the singlet sector (data generation, evolution, neural parton fitting, validation)
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Deeper understanding of neural parton fitting achieved (overlearning) stopping criterion, stability estimators ...)

Juan Roio-Chacón Progress in neural parton distributions

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- Non-singlet parton fitting completed.
- Be prepared for first neural parton set by summer 2007!

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EXTRA SLIDES

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Statistical estimators

	Total	NMC	BCDMS
$\chi^2_{ m tot}$	0.75	0.72	0.78
$\langle E \rangle$	2.27	1.99	2.52
$r [F_2^{NS}]$	0.81	0.66	0.95
$\left\langle \sigma^{(\exp)} \right\rangle_{\rm dat}$	0.011	0.017	0.006
$\left\langle \sigma^{(\text{net})} \right\rangle_{\text{dat}}$	0.006	0.009	0.004
$r\left[\sigma^{(\mathrm{net})} ight]$	0.59	-0.04	0.86
$\left< \rho^{(\exp)} \right>_{dat}$	0.11	0.39	0.16
$\left< \rho^{(\text{net})} \right>_{\text{dat}}$	0.46	0.42	0.50
$r\left[ho^{(m net)} ight]$	0.15	0.25	0.04
$\left< \operatorname{cov}^{(exp)} \right>_{\operatorname{dat}}$	8.6 10 ⁻⁶	$1.0 10^{-5}$	7.2 10^{-6}
$\left\langle \text{cov}^{(\text{net})} \right\rangle_{\text{dat}}$	$2.1 \ 10^{-5}$	$3.8 \ 10^{-5}$	$6.9 \ 10^{-6}$
$r \left[\operatorname{cov}^{(\operatorname{net})} \right]$	0.24	0.23	0.57

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3

Higher Twist

No evidence for Higher Twist found in experimental data:

Fit	$Q_{\min}^2 = 3 \text{ GeV}^2 + \text{HT}$	$Q_{\min}^2 = 5 \text{ GeV}^2$	$Q_{\min}^2 = 5 \text{ GeV}^2 + \text{HT}$
χ^2	0.76	0.79	0.78
$\left< d\left[q\right] \right>_{ m dat}$	2.9	0.8	3.2
$\left< d\left[q ight] ight>_{ m extra}$	1.4	0.8	0.9
$\langle d \left[\sigma_q \right] \rangle_{\text{dat}}$	1.2	1.5	1.9
$\left\langle d\left[\sigma_{q}\right] \right\rangle_{\mathrm{extra}}$	1.3	1.8	2.3

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Comparison to other approaches



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